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Name of Principal Author and all other author(s):

R. Shirkey, S. O'Brien, L. Parker, D. Quintis – ARL
S. Glasgow, T. Gach - TRAC

Principal Author's Organization and address:

Army Research Laboratory
Attn: AMSRD-ARL-CI-Ei
WSMR, NM 88002

Phone: (505) 678-5470 [DSN 258]

Fax: (505) 678-4449 [DSN 258]

Email: rshirkey@arl.army.mil

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Rule-based and Physics-based Weather Effects and Impacts for AWARS

Richard Shirkey*

Sean O'Brien

LeeLinda Parker

David Quintis

*U.S. Army Research Laboratory
Battlefield Environment Division
WSMR, NM 88002*

Steven R. Glasgow

Terry Gach

*TRADOC Analysis Center
Ft Leavenworth, KS 66027*

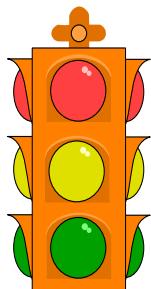
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Objective

Continue the current implementation of weather effects in the AWARS model using methodologies that improve the estimation of weather impacts in the target acquisition algorithms without increasing AWARS run time

Approach

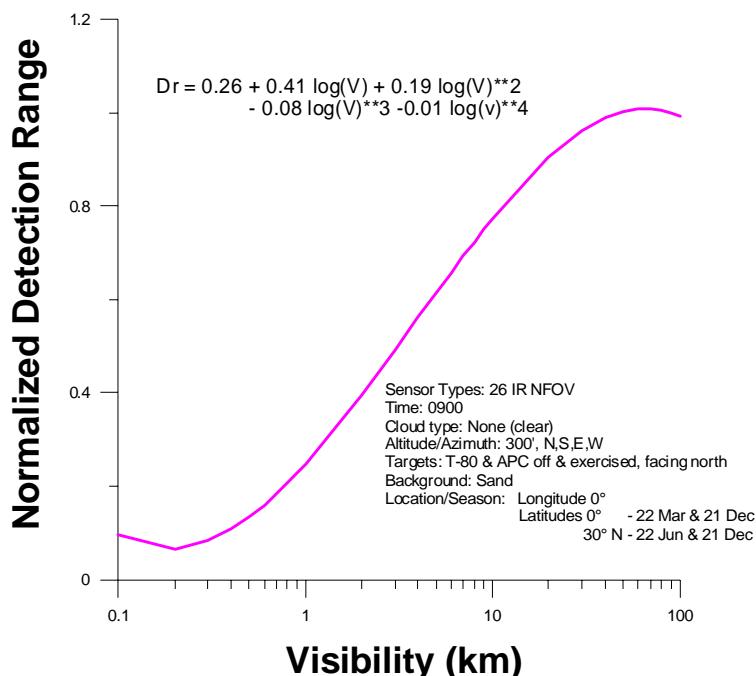
- Two complementary approaches are being examined
 - 1) Implementation of systems operation rules using the library from the Integrated Weather Effects Decision Aid (IWEDA)



- Unfavorable: Operations Prohibited
- Marginal: Operational Capability Degraded
- Favorable: No Operational Restrictions

Any occurrence of visibility < 2.9 miles reduces the range and reflectiveness and makes lasing the target difficult.

2) Implementation of parametric curves for acquisition ranges using the Target Acquisition Weapons Software (TAWS)

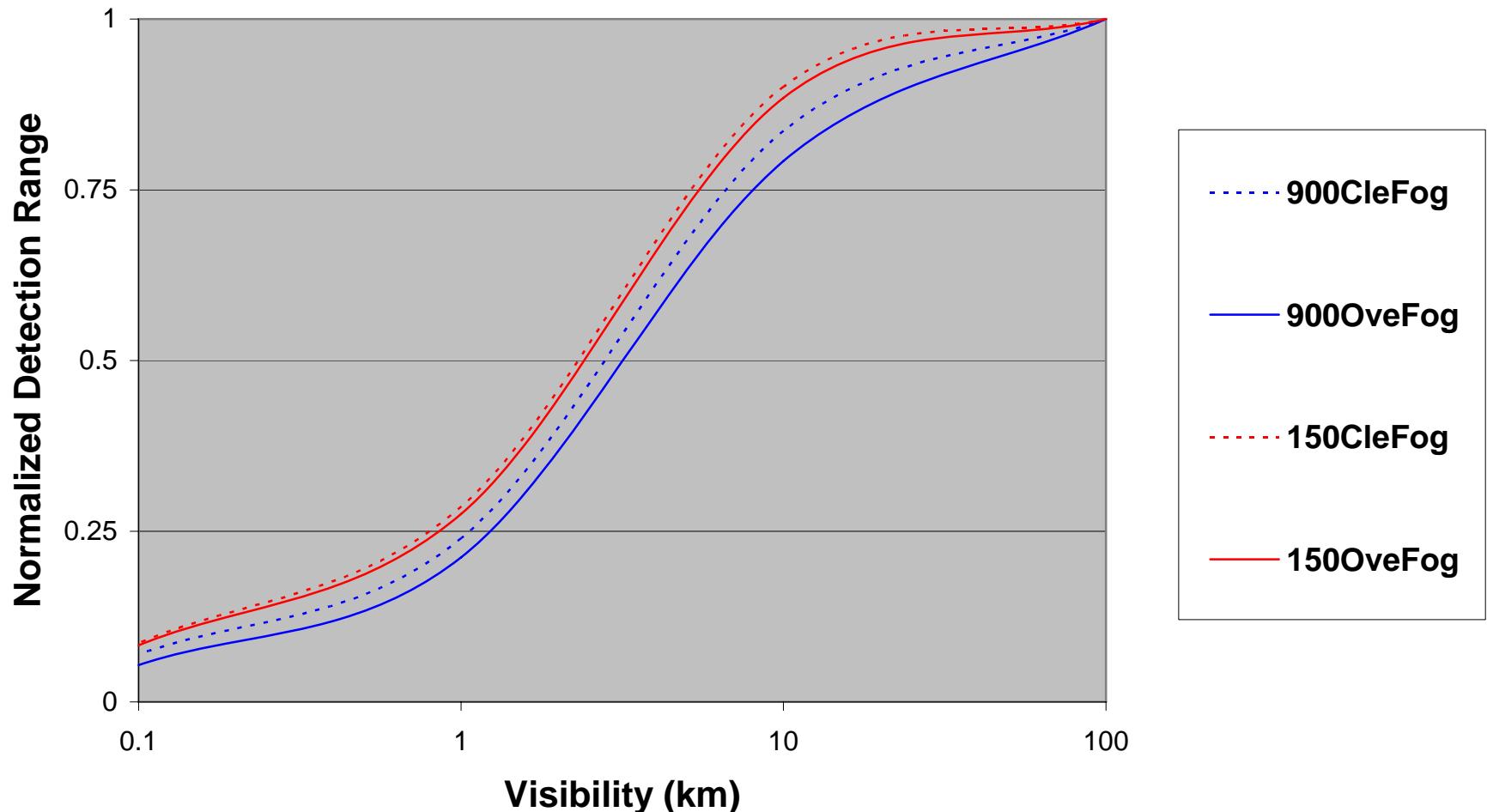


- Detection ranges from TAWS under varying visibilities have been normalized, curve fit and implemented in AWARS
- Direct replacement for target acquisition probability look-up tables

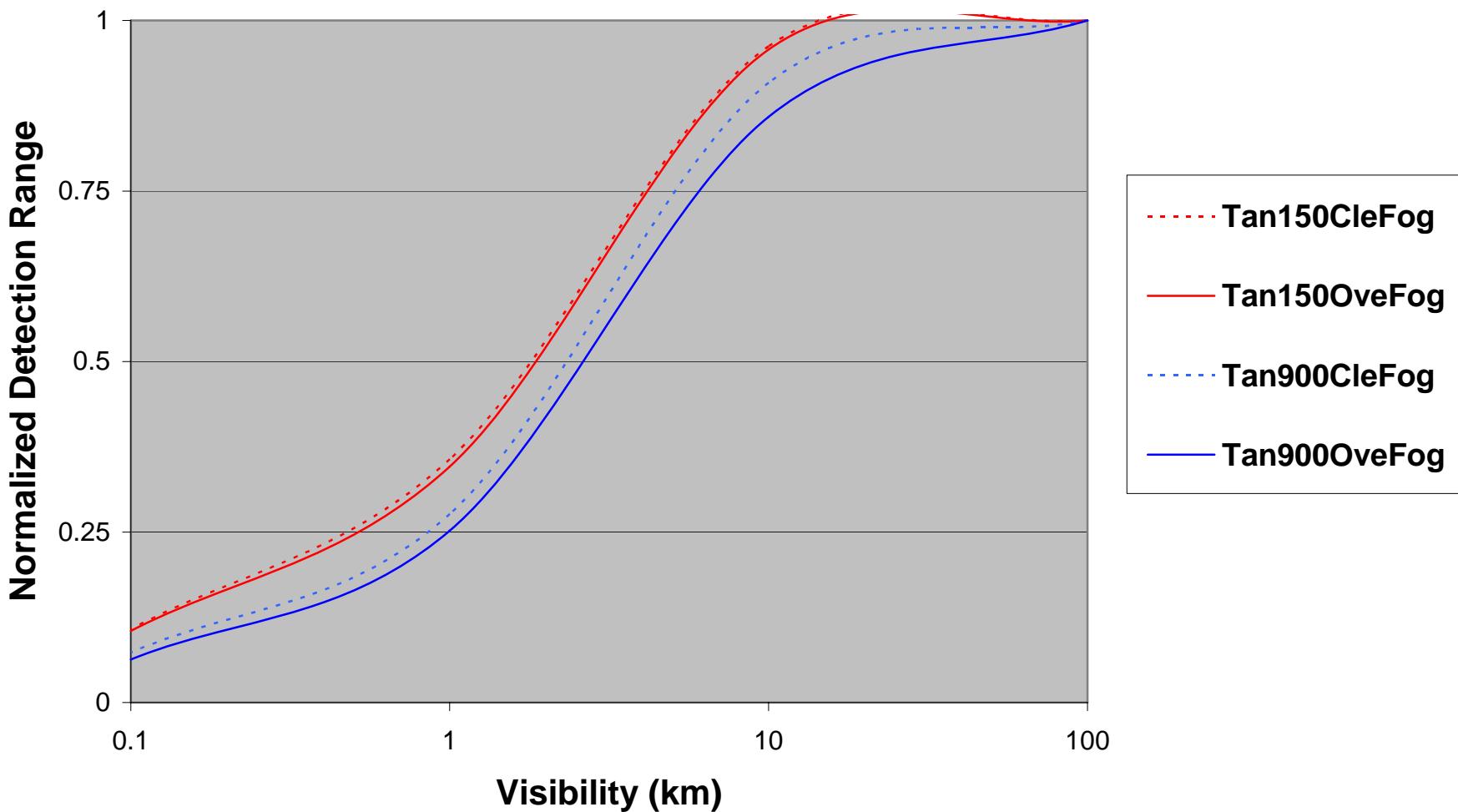
Scenario Conditions

Locale	Season
<ul style="list-style-type: none"> • 0° Longitude (Prime Meridian) • 0°, 30° N Latitudes 	<ul style="list-style-type: none"> • Equator: Equinox (22 Mar), Solstice (21 Dec) • 30° N: Summer (22 Jun), Winter (21 Dec)
Sensor/Target	LOS/Met
<ul style="list-style-type: none"> • 26 IR sensors • Targets <ul style="list-style-type: none"> • T72, APC • Off & Exercised • Background: Desert Sand 	<ul style="list-style-type: none"> • LOS Altitude/Azimuth: 300 ft / N, E, S, W • Met Visibility: 0.1, 1, 10, 100 km • Haze Aerosols: Rural, Advection Fog • Cloud Cover: Ac/As; Clear, Overcast

NFOV, Fog
f(TOD, Cloud Cover)

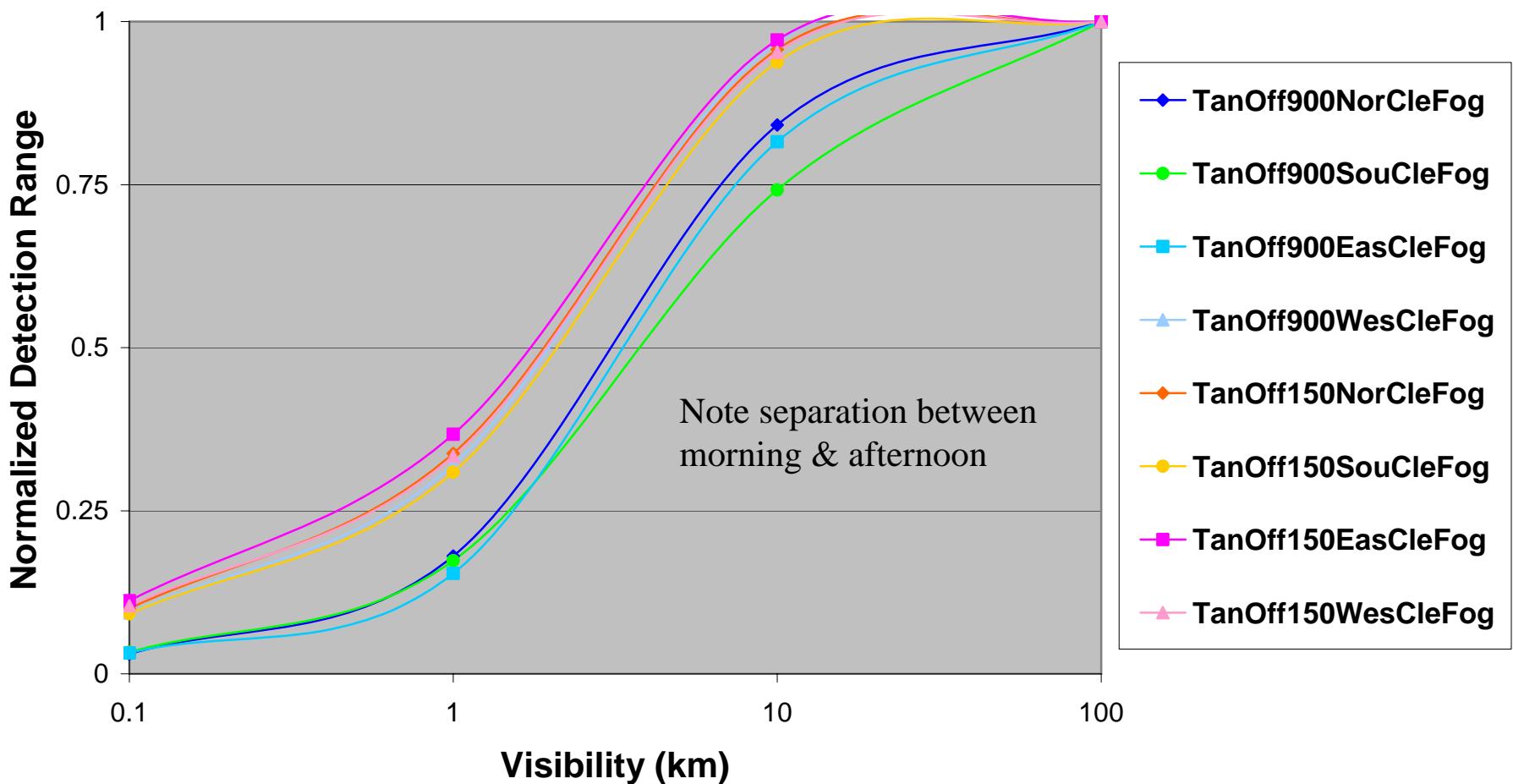


NFOV, Fog, Tank
 $f(\text{TOD} \& \text{Cloud Cover})$

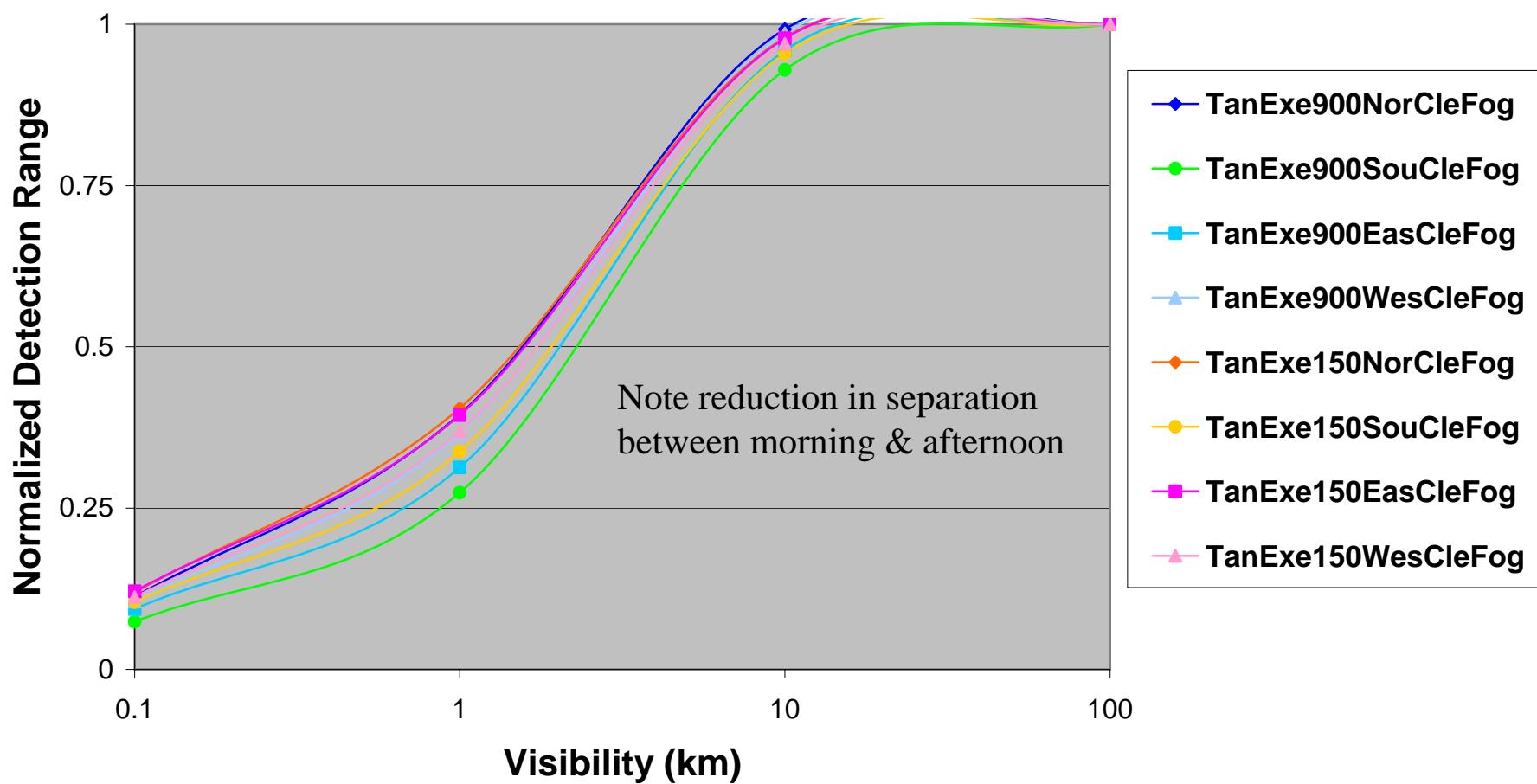


Average over: Sensors, seasons and locations

NFOV, Fog, Off Tank under cloudless skies f(TOD, Azimuth)

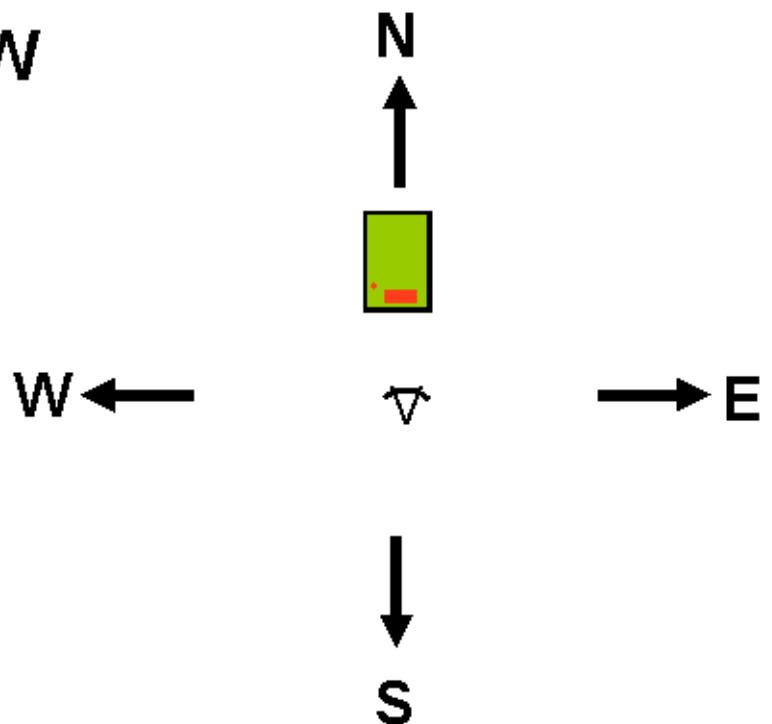


NFOV, Fog, **Exercised** Tank under cloudless skies f(TOD, Azimuth)

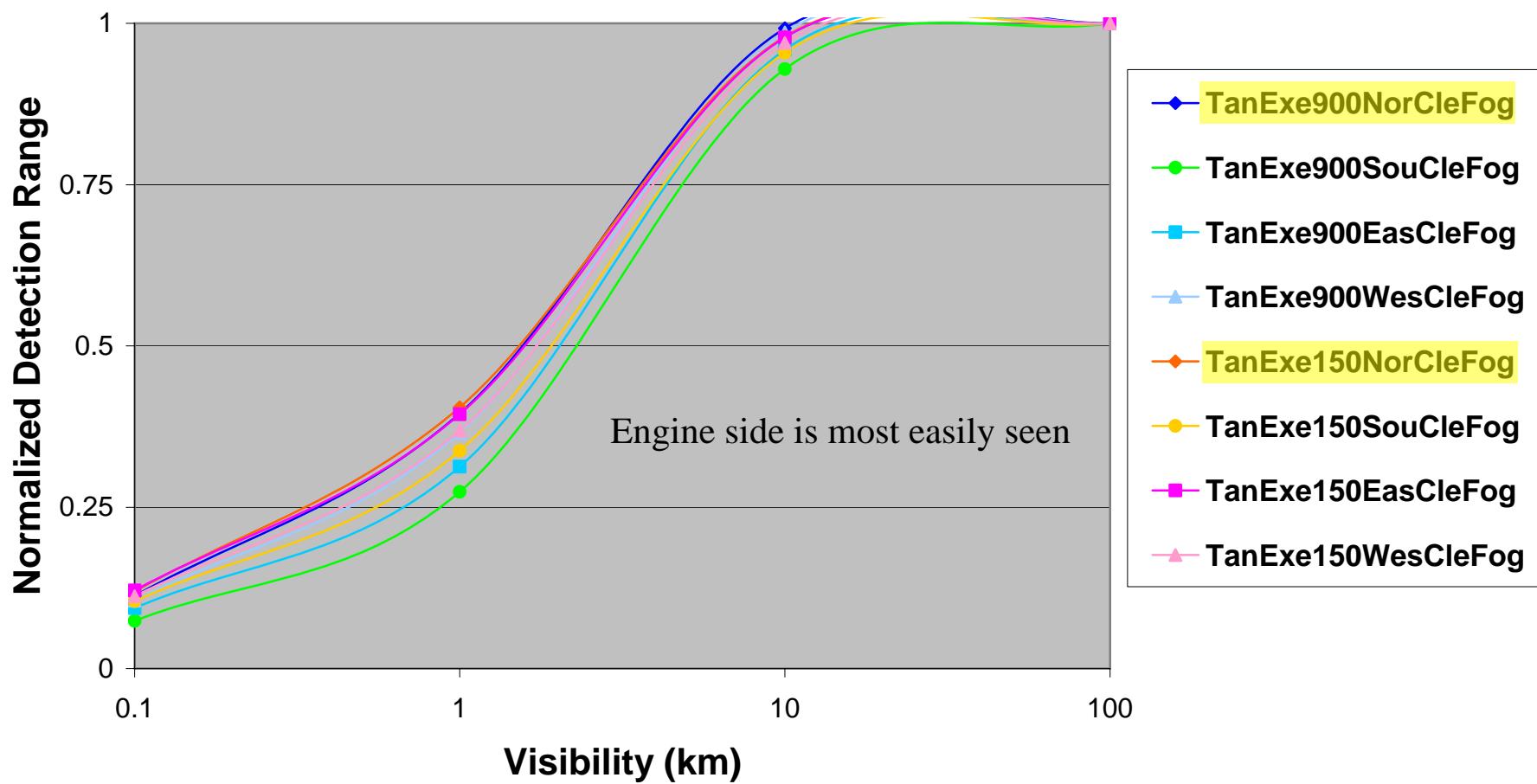


Sensor / Target Geometry

**NORTH
VIEW**

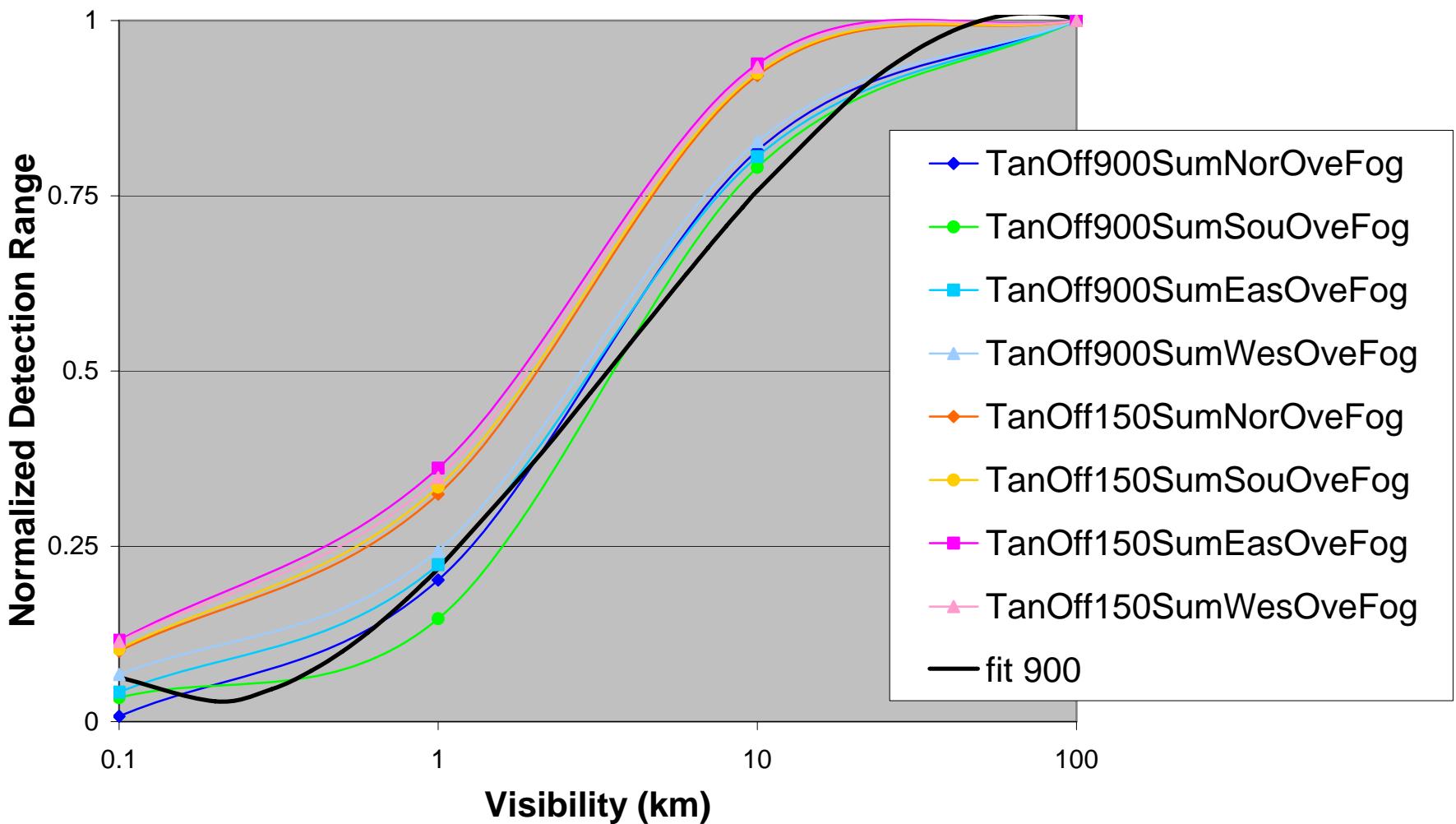


NFOV, Fog, **Exercised** Tank under cloudless skies f(TOD, Azimuth)



Example Curve Fit

NFOV, Fog, Off Tank under overcast skies, Summer
 $f(\text{TOD} \& \text{Azimuth})$
 (averages over: sensors & locations)



- Addition of UAV/FWA and GMU rules and implementation is in progress
- Helo and UAV IWEDA mobility checks have been extended to include more parameters:
 - Surface Wind speed
 - Surface Visibility
 - Basic weather condition (heavy rain, snow, etc.)
 - Cloud Cover (significant for UAV missions)
 - Cloud Base Height (affects aerial platform vulnerability)
 - Surface Temperature (affects mission effectiveness)

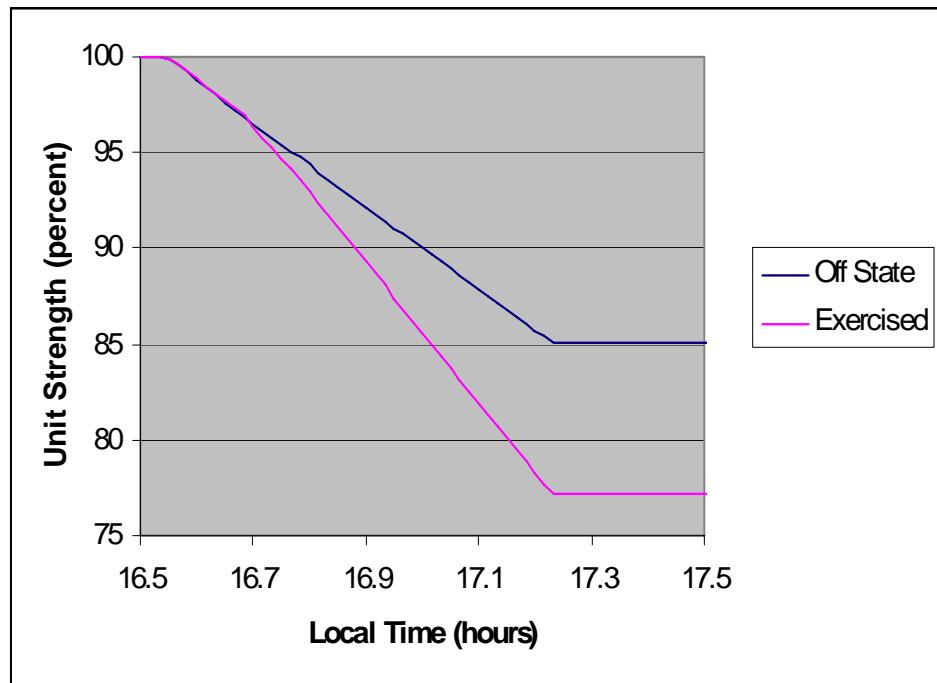
- New sensor curve fits
- Revised maximum sensor detection ranges
- Revised parametric averaging
 - Less aggregation of curve fits
 - Maximum detection ranges not aggregated

AWARS ARL Test Scenario

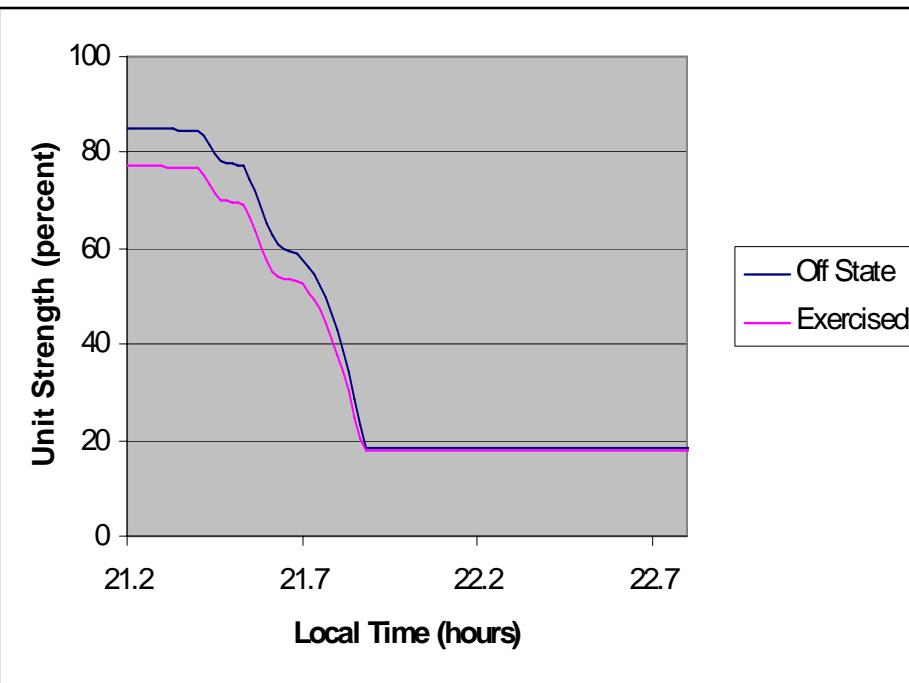
Target State Effects

Defending Red (R2110MX) Unit, 0.5 km Met Visibility, Fog

Under attack by Blue Helos



Under attack by Blue Ground Units

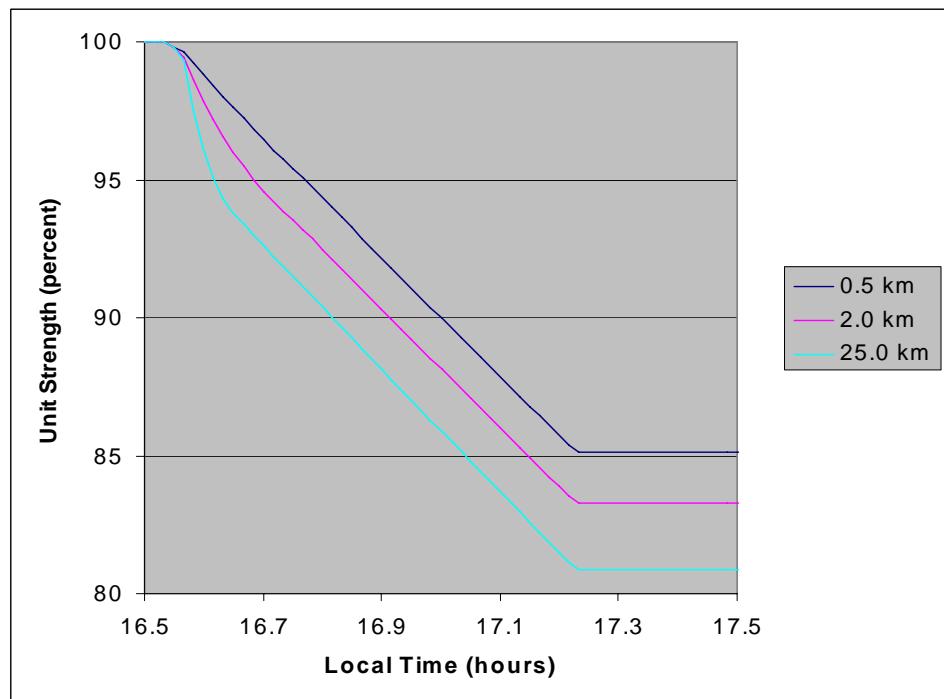


AWARS ARL Test Scenario

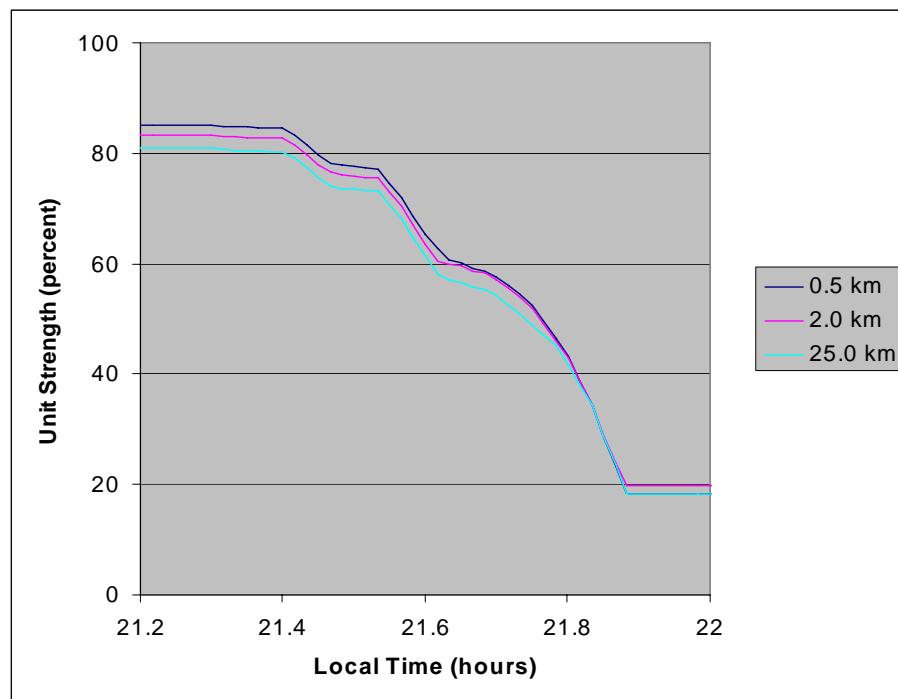
Met Visibility Effects

Defending Red (R2110MX) Unit, Off Target State, Fog

Under attack by Blue Helos



Under attack by Blue Ground Units



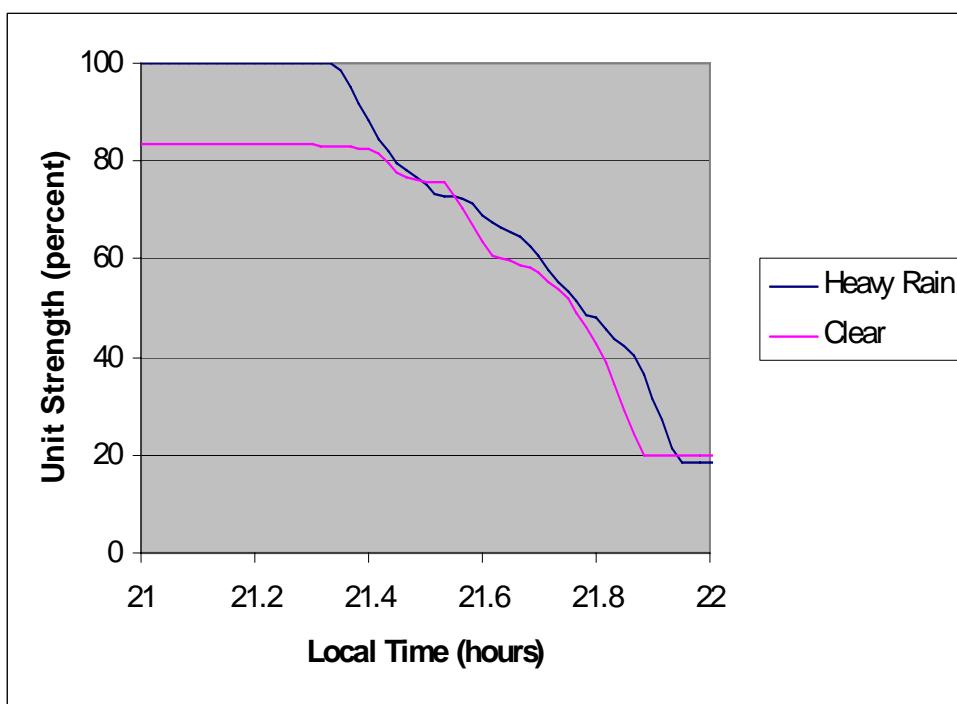
AWARS ARL Test Scenario

Basic Weather Condition Effects

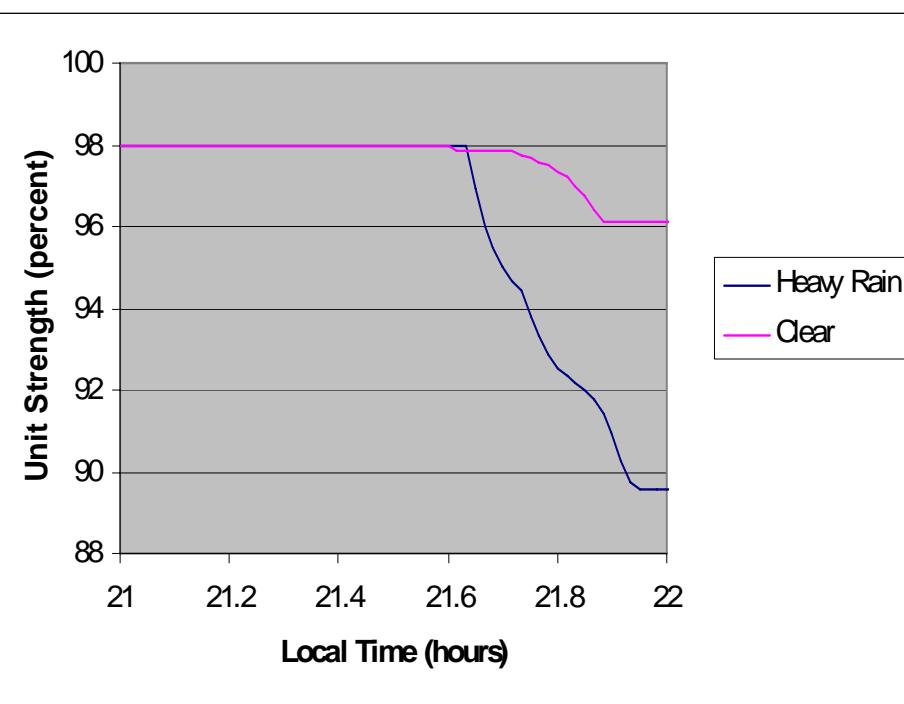


**Blue Attack Helos Grounded by Heavy Rain,
Off Target State, Fog, 2 km Met Visibility**

Red (R2110MX) Defending Unit



Blue (B2110MX) Attacking Unit



Each Terrain Cell within Weather Effect Area

- **Basic Condition**
 - Clear, fog/heavy fog, rain/heavy rain, snow/heavy snow
- **Multiple entries by elevation**
 - Temperature
 - Humidity
 - Cloud coverage
 - DF acquisition & visibility calculations
 - Wind
 - Velocity
 - Direction
 - Speed
 - Used for Chemical/Smoke Transport & Diffusion
 - Sky Condition based on cloud cover
 - Clear, overcast, or heavy overcast

Future Work

Conceptual Schema
dashed: do once
solid: as called

